

## **AMENDMENTS TO THE SPECIFICATION**

### **Please amend the first full paragraph on page 4 as follows:**

The present invention accordingly also provides an apparatus for locating a non-visible ~~objects-object~~ positioned behind an opaque surface, which apparatus comprises means to generate a variable strength magnetic field, a base member adapted to be placed on or against the surface, means in the base member defining a machining guide, an array of Hall effect sensors located relative to the machining guide, and means for collecting and ~~analysing-analyzing~~ outputs from at least some of the sensors to provide an indication of the variation of the magnetic field associated with the object relative to the position of the base member.

### **Please amend the first full paragraph on page 11 as follows:**

On the underside of the unit 31 and accordingly not visible in ~~Figure 2, Figure 3,~~ is an array of Hall effect sensors. These surround a drilling guide tube 33 in an appropriate arrangement, for example cruciform, though other arrangements can be contemplated.

### **Please amend the third full paragraph on page 11 as follows:**

Before using the apparatus, to locate one of the holes 22 not visible behind skin 21, a magnet is placed in one of the holes 22 so that a symmetrical magnetic field spreads out through the skin 21 and its field strength can be detected adjacent the surface of skin 21 visible in ~~Figure 2-Figure 3~~ by means of the Hall effect sensors on the underside of unit 31. Those sensors are connected to processing electronics located in unit 31.